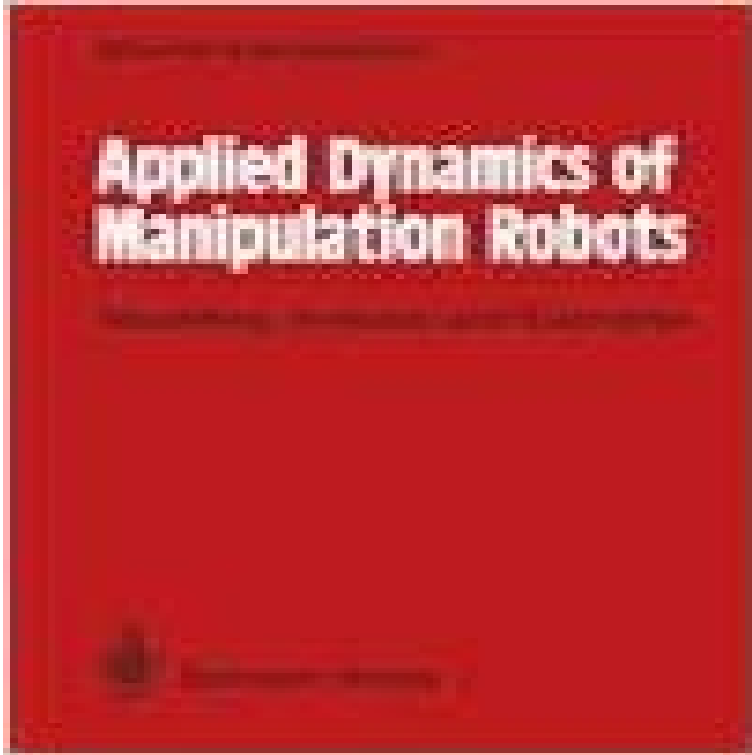


Applied Dynamics of Manipulation Robots: Modelling, Analysis and Examples



During the period 1982-1985, six books of the series: Scientific Fundamentals of Robotics were published by Springer-Verlag. In chronological order these were: Dynamics of Manipulation Robots: Theory and Application, by M. Vukobratovic and V. Potkonjak, Control of Manipulation Robots: Theory and Application, by M. Vukobratovic and D. Stokic, Kinematics and Trajectory Synthesis of Manipulation Robots, by M. Vukobratovic and H. Kircanski, Real-Time Dynamics of Manipulation Robots by M. Vukobratovic and N. Kircanski, Non-Adaptive and Adaptive Control of Manipulation Robots, by M. Vukobratovic, D. Stokic and N. Kircanski and Computer-Aided Design and Applied Dynamics of Manipulation Robots, by M. Vukobratovic and V. Potkonjak. Within the series, during 1989, two monographs dealing with new subjects will be published. So far, amongst the published monographs, Vol. 1 has been translated into Japanese, Volumes 2 and 5 into Russian, and Volumes 1-6 will appear in Chinese and Hungarian. In the authors opinion, the aforementioned monographs, in principle, cover with sufficient breadth, the topics devoted to the design of robots and their control systems, at the level of post-graduate study in robotics. However, if this material was also to apply to the study of robotics at under-graduate level, it would have to be modified so as to obtain the character of a textbook. With this in mind, it must be noted that the subject matter contained in the text cannot be simplified but can only be elaborated in more detail.

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